

For instance, the error in the first step is

$$e_1 = \phi(t_1) - y_1 = \frac{19e^{4\bar{t}_0}(0.0025)}{2}, \quad 0 < \bar{t}_0 < 0.05.$$

It is clear that  $e_1$  is positive, and since  $e^{4\bar{t}_0} < e^{0.2}$ , we have

$$e_1 \leq \frac{19e^{0.2}(0.0025)}{2} \cong 0.02901. \quad (27)$$

Note also that  $e^{4\bar{t}_0} > 1$ ; hence  $e_1 > 19(0.0025)/2 = 0.02375$ . The actual error is 0.02542. It follows from Eq. (26) that the error becomes progressively worse with increasing  $t$ ; this is also clearly shown by the results in Table 8.1.1. Similar computations for bounds for the local truncation error give

$$1.0617 \cong \frac{19e^{3.8}(0.0025)}{2} \leq e_{20} \leq \frac{19e^4(0.0025)}{2} \cong 1.2967 \quad (28)$$

in going from 0.95 to 1.0 and

$$57.96 \cong \frac{19e^{7.8}(0.0025)}{2} \leq e_{40} \leq \frac{19e^8(0.0025)}{2} \cong 70.80 \quad (29)$$

in going from 1.95 to 2.0.

These results indicate that, for this problem, the local truncation error is about 2500 times larger near  $t = 2$  than near  $t = 0$ . Thus, to reduce the local truncation error to an acceptable level throughout  $0 \leq t \leq 2$ , one must choose a step size  $h$  based on an analysis near  $t = 2$ . Of course, this step size will be much smaller than necessary near  $t = 0$ . For example, to achieve a local truncation error of 0.01 for this problem, we need a step size of about 0.00059 near  $t = 2$  and a step size of about 0.032 near  $t = 0$ . The use of a uniform step size that is smaller than necessary over much of the interval results in more calculations than necessary, more time consumed, and possibly more danger of unacceptable round-off errors.

Another approach is to keep the local truncation error approximately constant throughout the interval by gradually reducing the step size as  $t$  increases. In the example problem we would need to reduce  $h$  by a factor of about 50 in going from  $t = 0$  to  $t = 2$ . A method that provides for variations in the step size is called **adaptive**. All modern computer codes for solving differential equations have the capability of adjusting the step size as needed. We will return to this question in the next section.

## PROBLEMS

In each of Problems 1 through 6 find approximate values of the solution of the given initial value problem at  $t = 0.1, 0.2, 0.3$ , and  $0.4$ .

- Use the Euler method with  $h = 0.05$ .
- Use the Euler method with  $h = 0.025$ .
- Use the backward Euler method with  $h = 0.05$ .
- Use the backward Euler method with  $h = 0.025$ .

1.  $y' = 3 + t - y, \quad y(0) = 1$

2.  $y' = 5t - 3\sqrt{y}, \quad y(0) = 2$

3.  $y' = 2y - 3t, \quad y(0) = 1$

4.  $y' = 2t + e^{-ty}, \quad y(0) = 1$

5.  $y' = \frac{y^2 + 2ty}{3 + t^2}, \quad y(0) = 0.5$

6.  $y' = (t^2 - y^2) \sin y, \quad y(0) = -1$